EXHIBIT LL



CONTACT US WYVIEW CART

HOME PRODUCTS HOW TO BUY SUPPORT COMPANY

Downloads I2C Info Articles FAQ Returns Policy Contact

SPI Background

Print Version | Back

Related Links
SPI Glossary
Using the Aardvark
adapter with a Microwire
device

Related Products SPI Development Kit

Programming Kit

Cheetah SPI Host

Beagle I2C/SPI/MDIO

Protocol Analyzer

Aardvark I2C/SPI Host

Adapter

Adapter

Contents

- History
- · Theory of Operation
- Modes
- . Benefits and Drawbacks
- References

History

SPI is a serial communication bus developed by Motorola. It is a full-duplex protocol that functions on a master-slave paradigm that is ideally suited to data stream application.

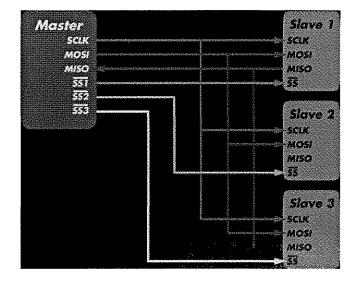
Тор

Theory of Operation

SPI requires four signals: clock (SCLK), master output/slave input (MOSI), master input/slave output (MISO), slave select (SS).

Three signals are shared by all devices on the SPI bus: SCLK, MOSI and MISO. SCLK is generated by the master device and is used for synchronization. MOSI and MISO are the data lines. The direction of transfer is indicated by their names. Data is always transferred in both directions in SPI, but an SPI device interested in only transmitting data can choose to ignore the receive bytes. Likewise, a device only interested in the incoming bytes can transmit dummy bytes.

Each device has its own SS line. The master pulls low on a slave's SS line to select a device for communication.



1 of 3 10/10/2007 7:43 PM

Figure 1: Sample SPI implementation. Each slave device requires a separate slave select signal (SS).

The exchange itself has no pre-defined protocol. This makes it ideal for data-stream applications. Data can be transferred at high speed, often into the range of the tens of megahertz. The flip side is there is no acknowledgement, no flow control, the master may not even be aware of the slave's presence.

Тор

Modes

The exchange itself has no pre-defined protocol. This makes it ideal for data-streaming applications. Data can be transferred at high speed, often into the range of the tens of megahertz. The flip side is that there is no acknowledgment, no flow control, and the master may not even be aware of the slave's presence.

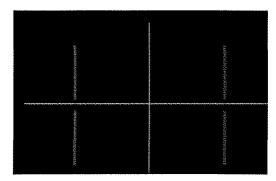


Figure 2: SPI Modes
The frame of the data exchange is
described by two parameters, the clock
polarity (CPOL) and the clock phase
(CPHA). This diagram shows the four
possible states for these parameters and
the corresponding mode in SPI.

Тор

Benefits and Drawbacks

SPI is a very simple communication protocol. It does not have a specific high-level protocol which means that there is almost no overhead. Data can be shifted at very high rates in full duplex. This makes it very simple and efficient in a single master single slave scenario.

Because each slave needs its own SS, the number of traces required is n+3, where n is the number of SPI devices. This means increased board complexity when the number of slaves is increased.

<u> Тор</u>

References

- Introduction to Serial Peripheral Interface Embedded.com
- SPI Serial Peripheral Interface

Back | Top

2 of 3 10/10/2007 7:43 PM

© 2001-2007 Total Phase, Inc. All rights reserved. Terms of Use | Privacy Notice

HOME | PRODUCTS | HOW TO BUY | SUPPORT | COMPANY | CONTACT

10/10/2007 7:43 PM 3 of 3